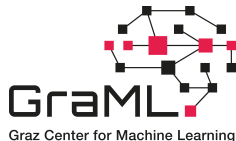


Improving Data-Driven Systems with Differential Equations – Approaches and Open Problems

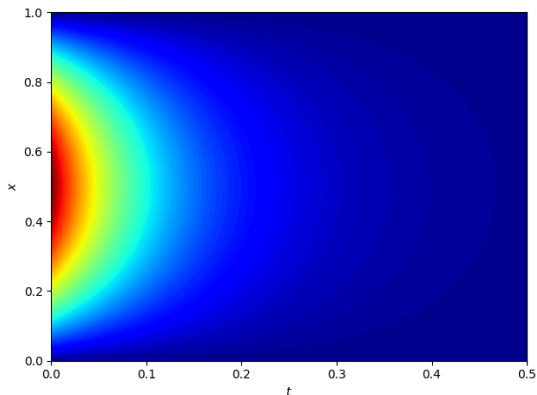
Bernhard C. Geiger

Signal Processing and Speech Communication Laboratory
Graz University of Technology

MaritimeMET Workshop: Role of Metrology for Greener Shipping
April 16th 2026

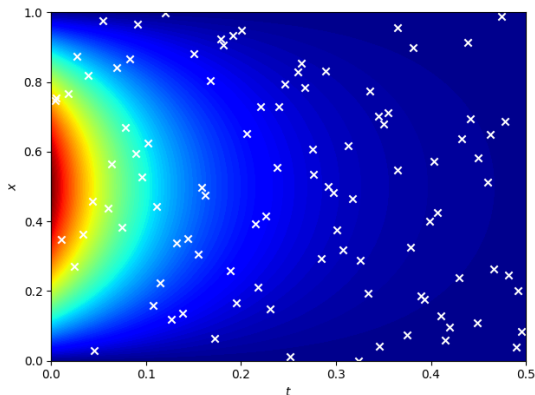


Motivation: Heat Equation



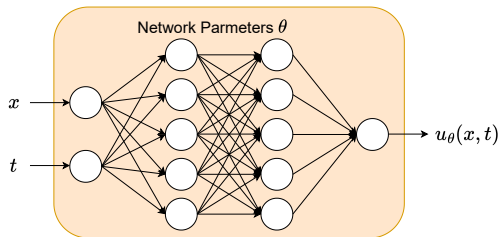
Task: Find approximation $u_{\theta}(x, t)$ to the true $u(x, t)$

Motivation: Heat Equation



Task: Find approximation $u_{\theta}(x, t)$ to the true $u(x, t)$

Vanilla NN

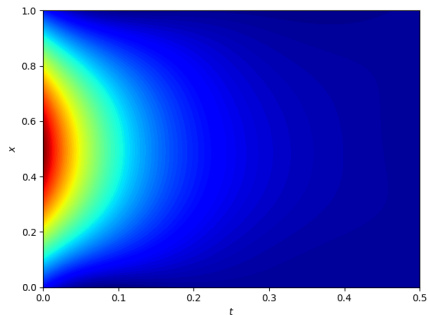
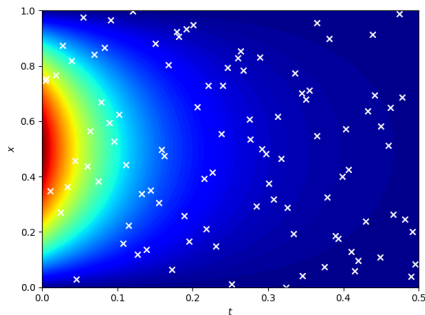


- $\mathcal{D} = \{(x_i, t_i, u_i = u(x_i, t_i))\}_{i=1, \dots, N}$
- MLP 20-20, tanh
- squared error loss $\ell(u, u_{\theta}) = (u - u_{\theta})^2$
- Adam optimizer

$$\theta^{\bullet} \in \operatorname{argmin}_{\theta \in \Theta} \frac{1}{|\mathcal{D}|} \sum_{(x_i, t_i, u_i) \in \mathcal{D}} \|u_i - u_{\theta}(x_i, t_i)\|^2$$

Vanilla NN (cont'd)

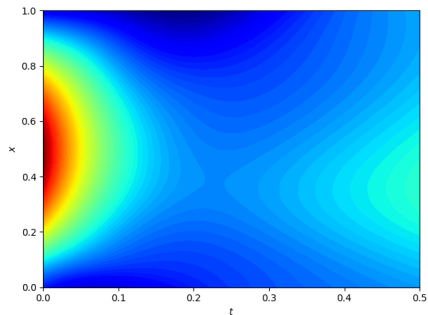
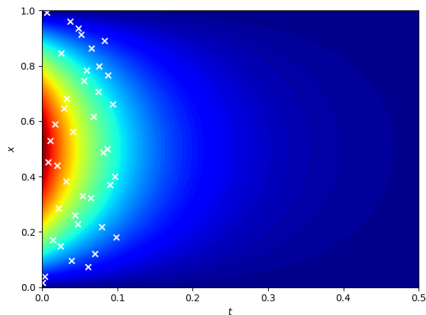
$\mathcal{D}$ from $\Omega = [0, 0.5] \times [0, 1]$, $|\mathcal{D}| = 100$



Rel. L2-Error: $\approx 2\text{-}3\%$

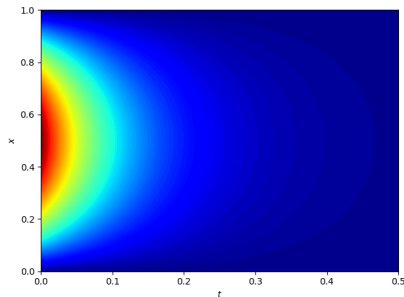
Vanilla NN (cont'd)

$\mathcal{D}$ from $[0, 0.1] \times [0, 1]$, $|\mathcal{D}| = 40$



Rel. L2-Error: $\approx 60\text{-}80\%$

Heat Equation Revisited



- Governing equation:

$$\frac{\partial}{\partial t} u(x, t) - \frac{\partial^2}{\partial x^2} u(x, t) = 0$$

- Initial condition:

$$u(x, 0) = \sin(\pi x)$$

- Boundary conditions:

$$u(0, t) = u(1, t) = 0$$

Physics-Informed Neural Networks (PINNs)

Idea: Ensure that u_θ satisfies the differential equation on the whole computational domain Ω

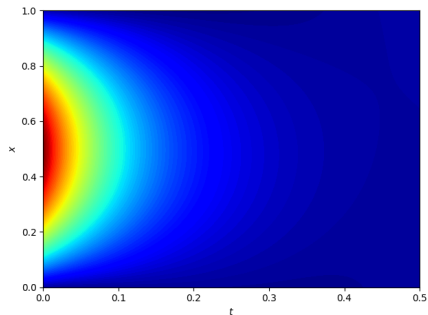
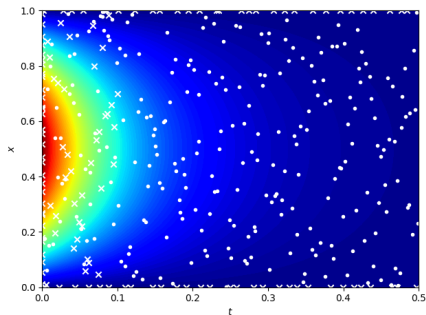
- sample *collocation points* $\mathcal{C}$ from Ω
- add regularization term that penalizes if u_θ violates physics at $\mathcal{C}$
- implement via automatic differentiation

$$\theta^\bullet \in \operatorname{argmin}_{\theta \in \Theta} \frac{1}{|\mathcal{D}|} \sum_{(x_i, t_i, u_i) \in \mathcal{D}} \|u_i - u_\theta(x_i, t_i)\|^2 + \lambda \frac{1}{|\mathcal{C}|} \sum_{(x_i, t_i) \in \mathcal{C}} \|u_{\theta,t}(x_i, t_i) - u_{\theta,xx}(x_i, t_i)\|^2$$

M. Raissi & al. "Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations".
Journal of Computational Physics 378:686-707, (2023)

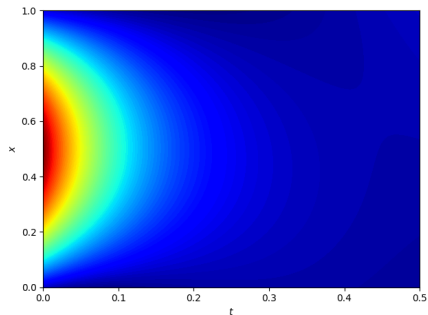
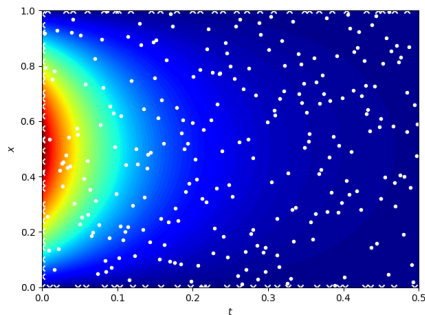
PINNs (cont'd)

$\mathcal{D}$ from $[0, 0.1] \times [0, 1] + \text{IC/BC}$, $|\mathcal{D}| = 100$, $|\mathcal{C}| = 250$, $\lambda = 1$



Rel. L2-Error: $\approx 1.5\%$

$\mathcal{D}$ from IC/BC, $|\mathcal{D}| = 60$, $|\mathcal{C}| = 250$, $\lambda = 1$



Rel. L2-Error: $\approx 5\%$

PINNs – Preliminary Summary

- PINNs are the “epitome” of physics-informed machine learning
- surrogate model for partial/ordinary differential equations
- physics information included in a regularization term
- can be used
 - to solve differential equations (replace classical solvers)
 - to solve inverse problems, e.g., determine parameters of the ODE/PDE
 - in hybrid settings, e.g., learning pressure field from velocity field

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PINNs can improve extrapolation performance of neural surrogates u_θ if there is little or no data.

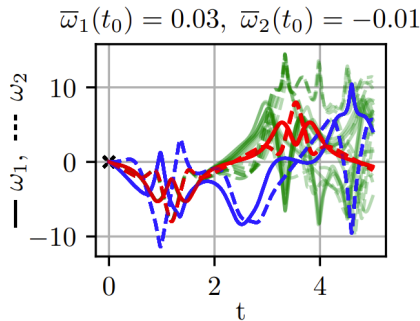
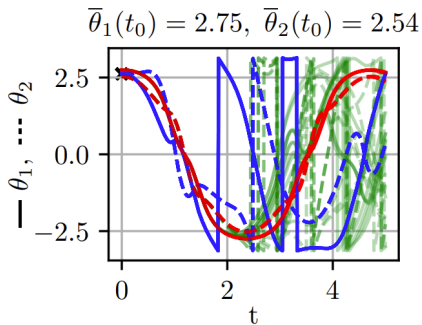
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But training PINNs is hard...

PINNs – Training Troubles



— RK45

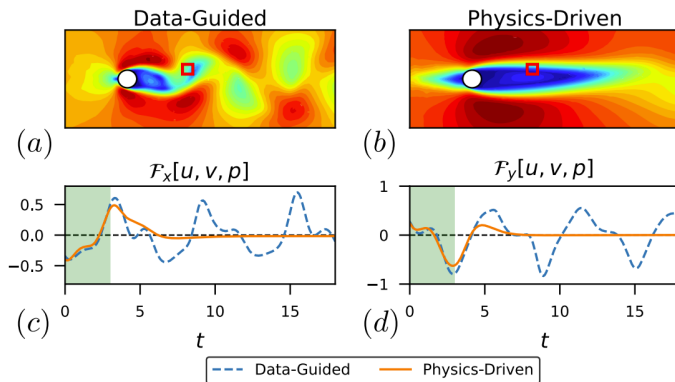
— PINN

— RK45_{shifted}

© Sophie Steger

S. Steger & al. "How PINNs cheat: Predicting chaotic motion of a double pendulum".
DLDE Workshop @ NeurIPS (2022)

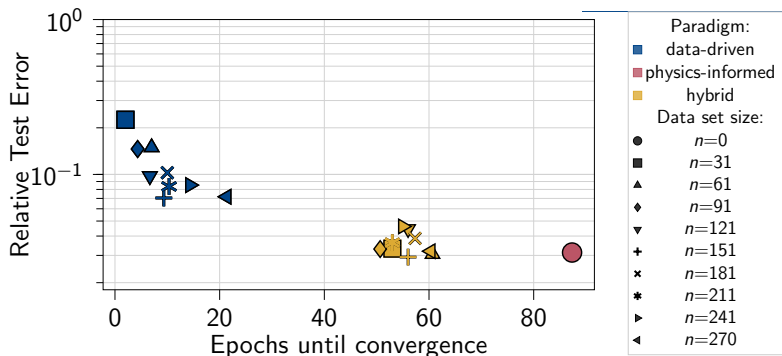
PINNs – Training Troubles



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F. M. Rohrhofer & al. "On the Role of Fixed Points of Dynamical Systems in Training Physics-Informed Neural Networks". TMLR 1/2023

PINNs – Training Troubles



Open Access (CC-BY)

M. Wellenhof-Karner & al. "Data and Modeling Assumptions in Physics-Informed Operator Learning". Differentiable Systems and Scientific Machine Learning Workshop @ EurIPS (2025)

Remedies?

- **Training schemes:** loss weighting, collocation point weighting, domain decomposition, curriculum learning, adaptive activation functions, ensemble/Bayesian approaches, hard-encoded IC/BCs,...
- **Model parameterization:** include prior knowledge about u in the inductive bias of the NN (characteristics-informed NNs, etc.)
- **Domain-Decomposition, Linearization, and ELMs:** no backpropagation, regularized linear least-squares.

U. Braga-Neto, "Characteristics-Informed Neural Networks for Forward and Inverse Hyperbolic Problems". arXiv (2023)

F. M. Rohrhofer & al., "Approximating families of sharp solutions to Fisher's equation with physics-informed neural networks". Computer Physics Communications 307:109422 (2025)

S. Anderson & al., "ELM-FBPINNs: An Efficient Multilevel Random Feature Method". arXiv (2024)

Conclusions

- machine learning should use knowledge, not only data
- physics-informed machine learning is domain and application specific
- PINNs can utilize differential equations, but
 - must be adapted to the respective problem
 - suffer from training instabilities
 - require a larger number of computations for training
- **energy-performance trade-off** of physics-informed machine learning is still poorly understood

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Thanks!